#### CSCI 5541: Natural Language Processing

Lecture 7: Language Models: RNN, LSTM, and Seq2Seq





#### Announcement (0213)

- □ Minor HW2 Revisions --> See slack announcement
- □ HW3 is released. The due date is due Tue, Feb 25.

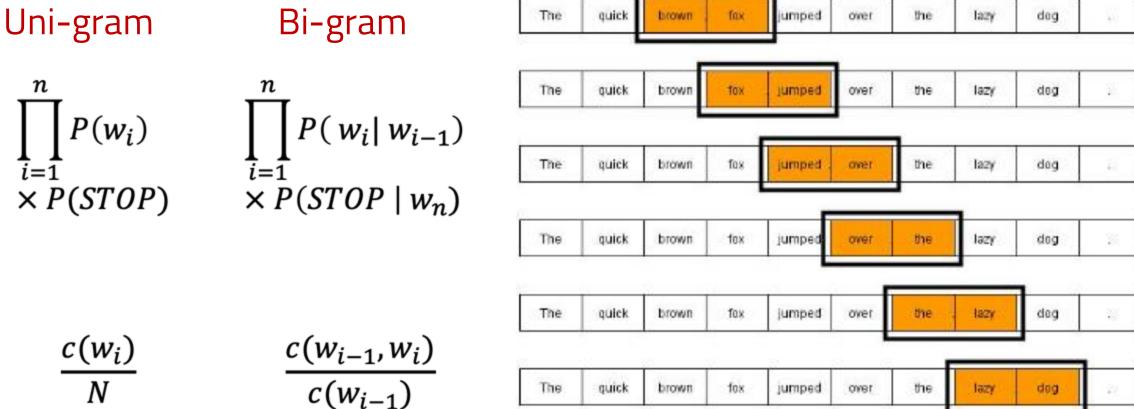
Project

- o Brainstorming is due next Tuesday, Feb 18
- o Groups have been assigned in slack
- There are a couple of students not yet in groups. If you have a fully formed group and are willing to take on someone else, let me know.



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The	quick	brown	fox	jumped	over	the	lazy	deg	
					Ľ			9	
The	quick	brown	fox	jumped	over	the	lazy	dog	1







## Sparsity in Ngram LM

	i	want	to	eat	chinese	food	lunch	spend
i	5	827	0	9	0	0	0	2
want	2	0	608	1	6	6	5	1
to	2	0	4	686	2	0	6	211
eat	0	0	2	0	16	2	42	0
chinese	1	0	0	0	0	82	1	0
food	15	0	15	0	1	4	0	0
lunch	2	0	0	0	0	1	0	0
spend	1	0	1	0	0	0	0	0

Figure 4.1 Bigram counts for eight of the words (out of V = 1446) in the Berkeley Restaurant Project corpus of 9332 sentences. Zero counts are in gray.

$$\frac{c(w_{i-1}, w_i)}{c(w_{i-1})} \longrightarrow \frac{c(w_{i-1}, w_i) + \alpha}{c(w_{i-1}) + V\alpha}$$

2

$$P(w_{i} | w_{i-2}, w_{i-1}) = \lambda_{1} P(w_{i} | w_{i-2}, w_{i-1}) \\ + \lambda_{2} P(w_{i} | w_{i-1}) \\ + \lambda_{3} P(w_{i})$$





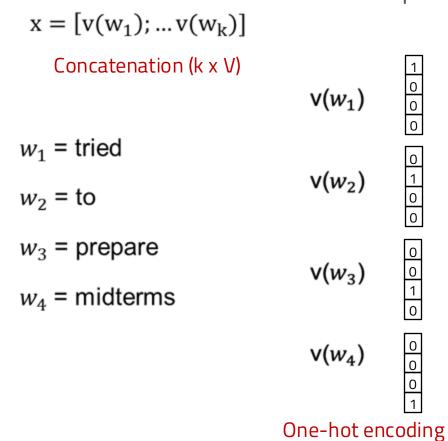
# Ngram LM vs Neural LM

To avoid the data sparsity problem from the ngram LM

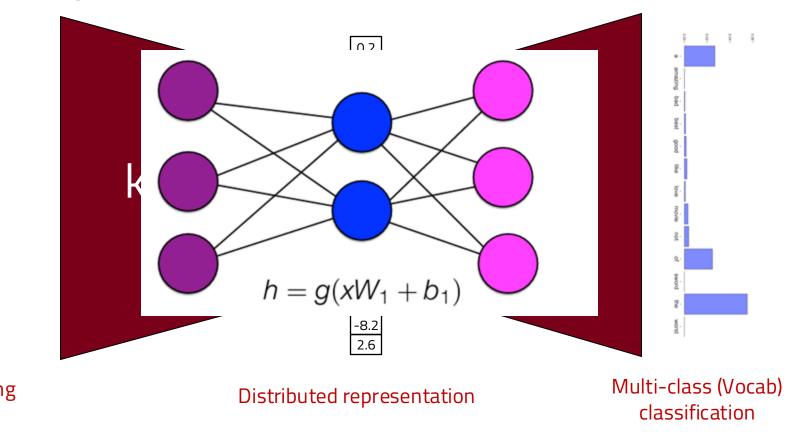


Neural LM





Simple feed-forward multilayer perceptron (e.g., one hidden layer)

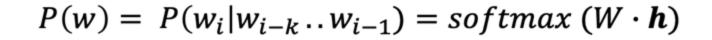


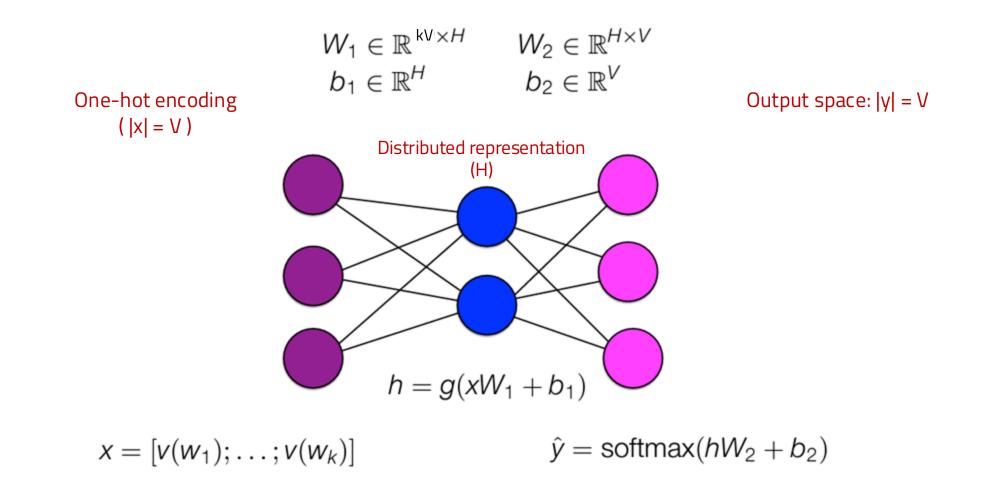
Bengio et al. 2003, A Neural Probabilistic Language Model



#### Neural LM





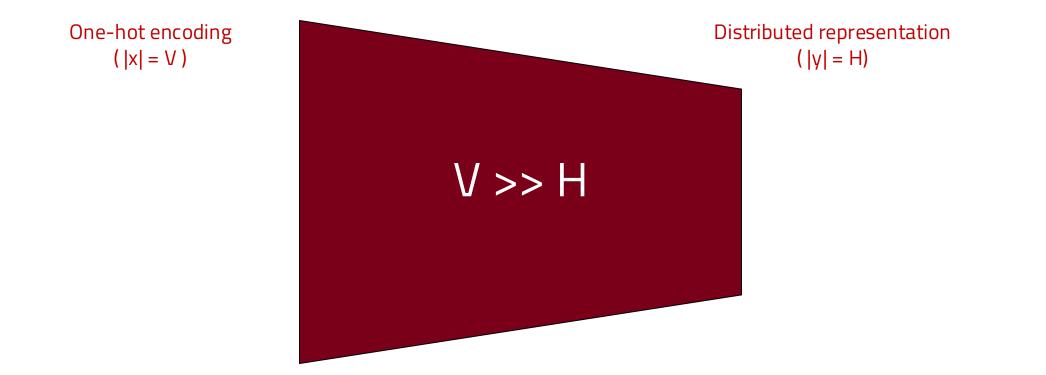




#### Neural LM



Represent high-dimensional words (and contexts) as low-dimensional vectors







#### Conditioning context (X [k x V])

tried to prepare midterm but I was too tired of...

Next word to predict (Y)

Context window size: k=4







#### Conditioning context (X [k x V])

trie<mark>d to prepare midterm but I</mark> was too tired of...

Next word to predict (Y)

Context window size: k=4







#### Conditioning context (X [k x V])

tried t<mark>o prepare midterm but I was</mark> too tired of...

Next word to predict (Y)

Context window size: k=4

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# Neural LM against Ngram LM



Pros

- No sparsity problem
- Don't need to store all observed n-gram counts

Cons

- □ Fixed context window is too small (larger window, larger W)
  - o Windows can never be large enough
- Different words are multiplied by completely different weights (W); no symmetry in how the inputs are processed.



#### Outline

Linearization: A general heuristic for model improvement

- Recurrent Neural Network (RNN)
- □ Long Short-term Memory (LSTM)
- Implementation of RNN and LSTM using PyTorch
- Sequence-to-Sequence modeling
- Teaser: Transformer-based LMs
- □ Why language models are useful?



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#### How do we make a better model?





#### More Params are Better

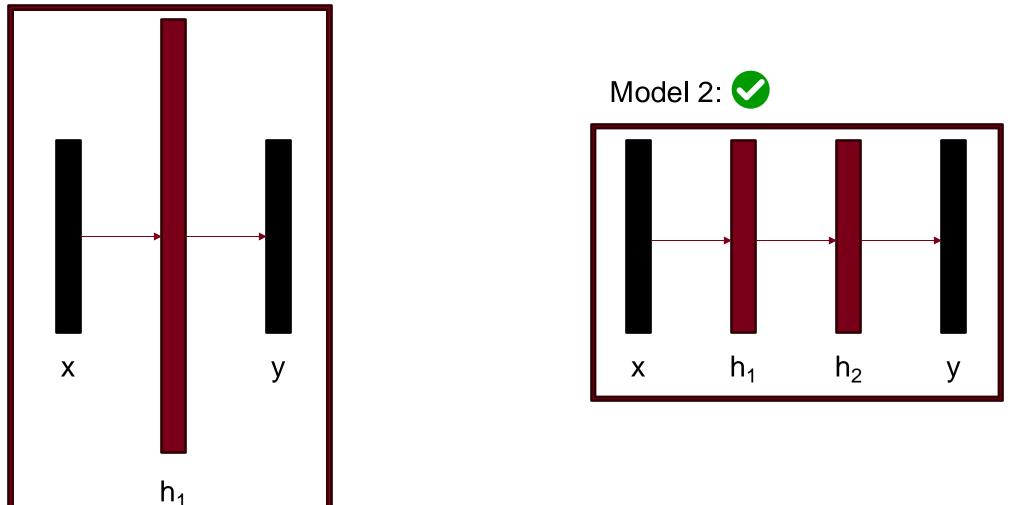


Better models have more weights





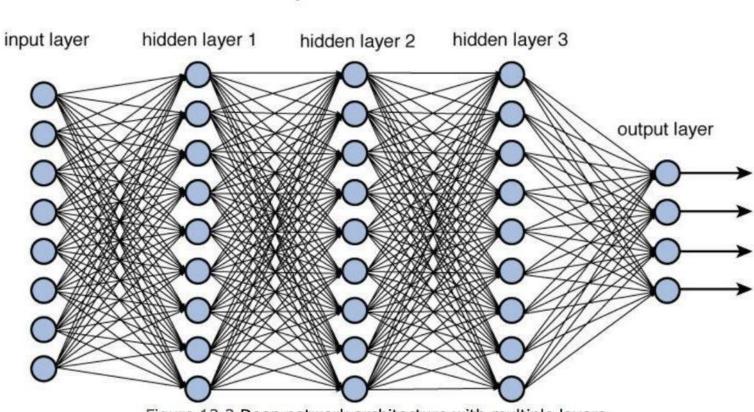
# Increasing depth is more efficient than width



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#### ...but very deep models are harder to train

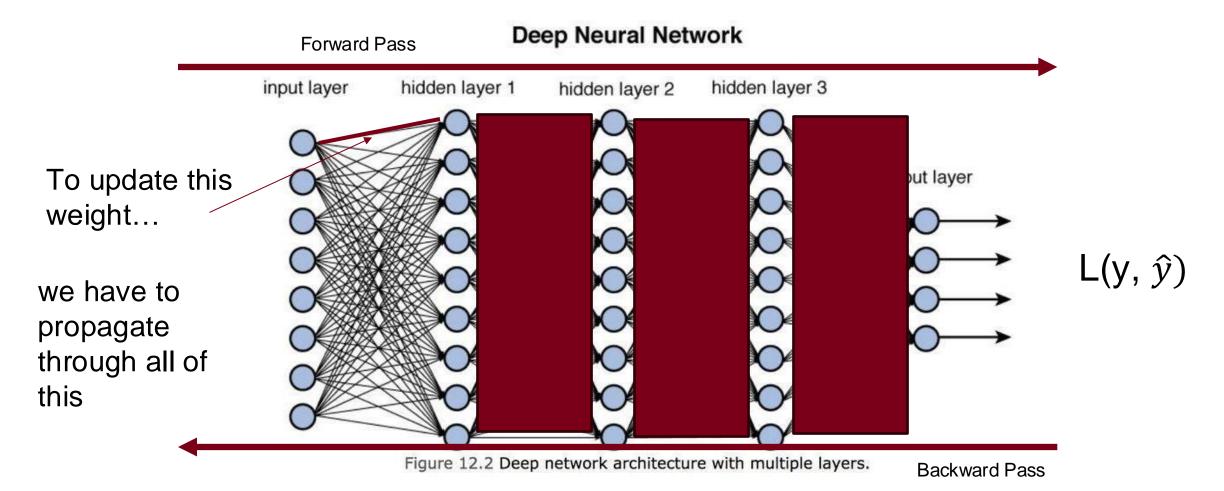


**Deep Neural Network** 

Figure 12.2 Deep network architecture with multiple layers.



# Why is this so challenging?





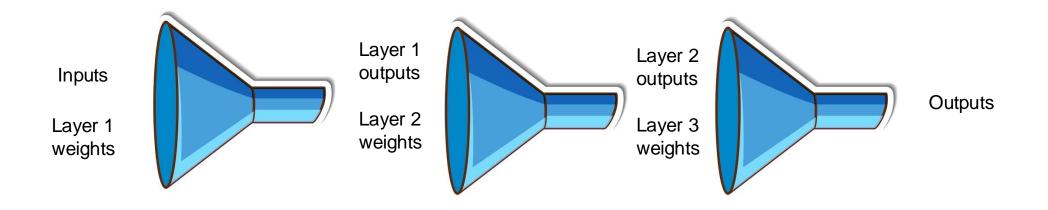
#### Analogy #1: A Game of Telephone







#### Analogy #2: A funnel of information

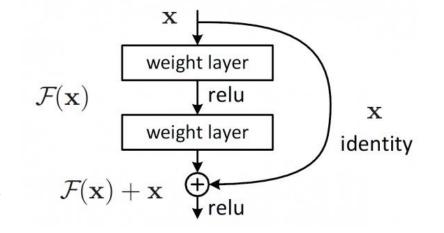


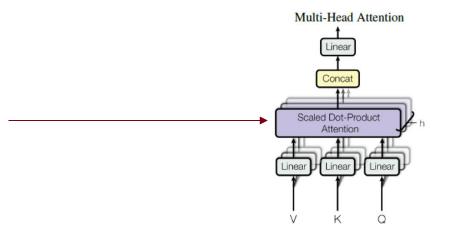


#### Linearization and Det-Bottlenecking

❑ Linearization → We need a better way to reduce the number of operations performed between our weights and our loss function (Residual connections)

□ De-Bottlenecking → We need a better way to ensure we are not bottlenecking any representations into some channel which is too small to contain all the information we need (Attention mechanism → later)







#### Outline

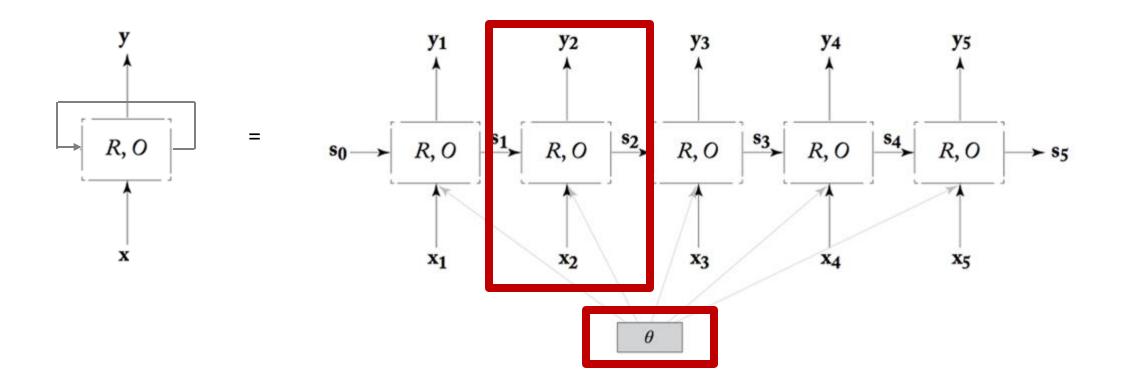
Linearization: A general heuristic for model improvement

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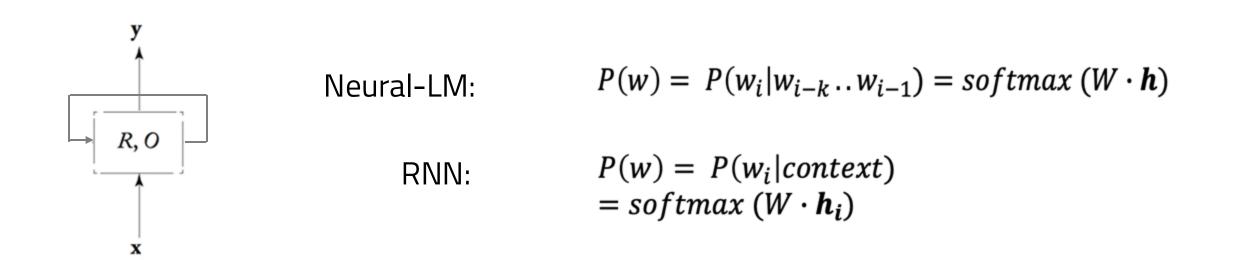
#### Recurrent Neural Network (RNN)

RNN allow arbitarily-sized conditioning contexts; condition on the entire sequence history.



Goldberg 2017





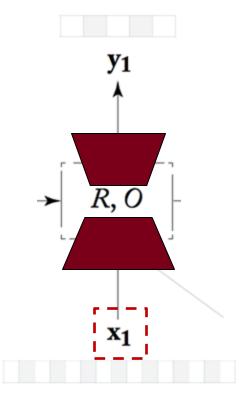




□ Each time set has two inputs:

 $\Box X_i$  (the observation at time step *i*):

One-hot vector, feature vector, or distributed
 representation of input token at *i* step

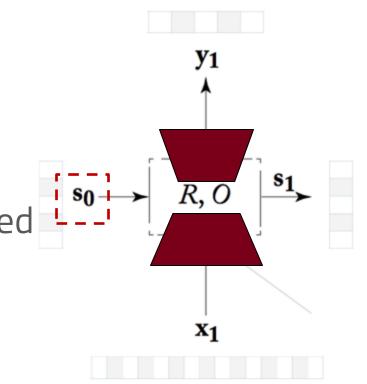




Each time set has two inputs:

 $\Box X_i$  (the observation at time step *i*):

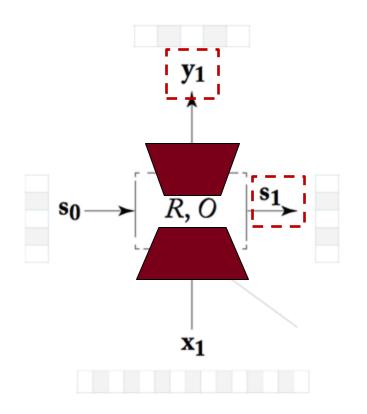
- One-hot vector, feature vector, or distributed representation of input token at *i* step
- □  $S_{i-1}$  (the output of the previous state): • Base case:  $S_0 = 0$  vector



□ Each time set has two outputs:

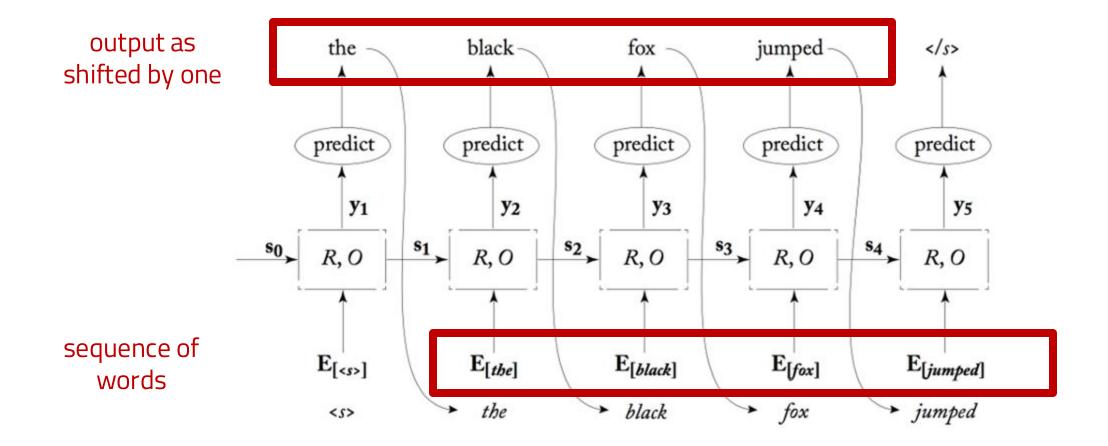
S<sub>i</sub> = R (X<sub>i</sub>, S<sub>i-1</sub>)
 R computes the output state as a function of the *current input* and *previous state*

y<sub>i</sub> = O (S<sub>i</sub>)
 O computes the output as a function of the *current output state*

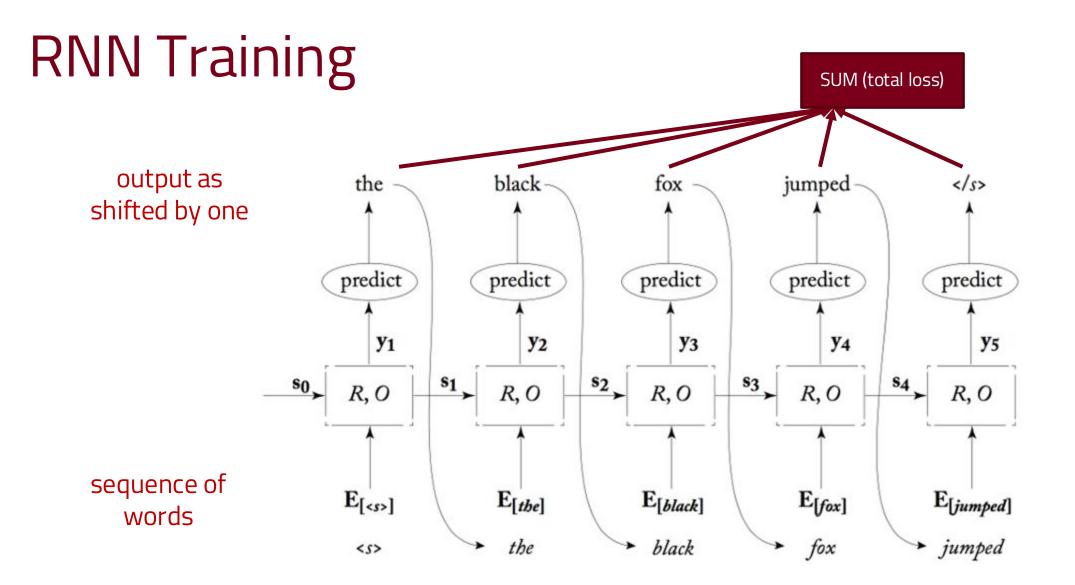




# **RNN** Training



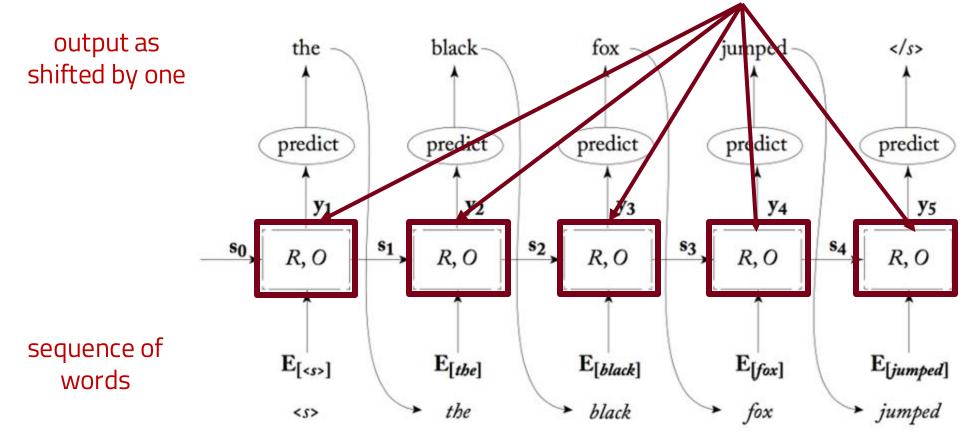






# **RNN** Training

#### Parameters are shared! Derivatives are accumulated.





#### What can RNNs do?

#### Represent a sentence

o Read whole sentence, make a prediction

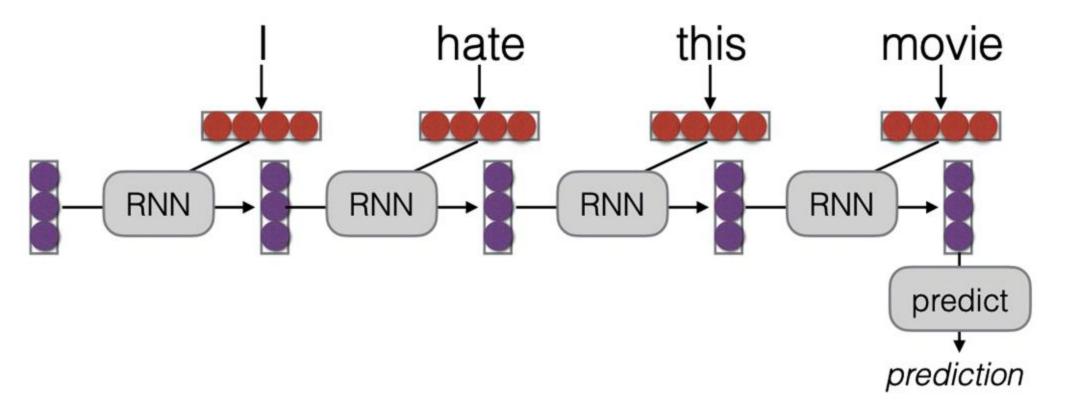
Represent a context within a sentence

o Read context up until that point



#### **Representing Sentences**

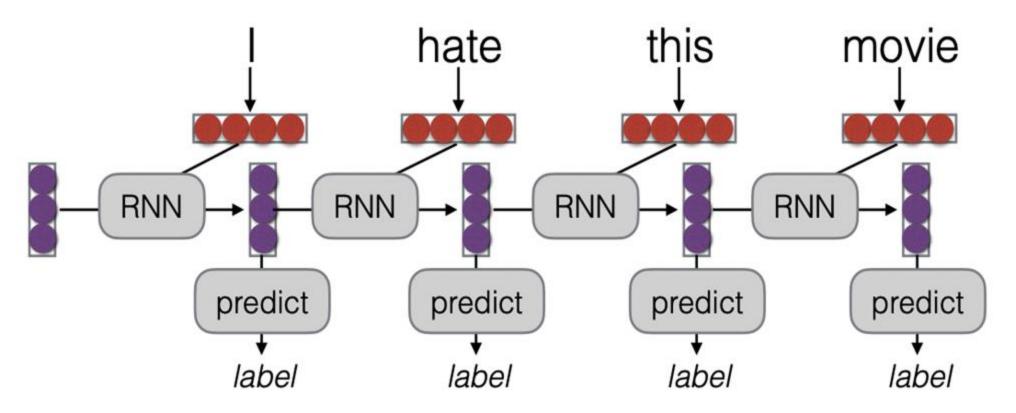
- Sentence classification
- Conditioned generation





#### Representing Context within Sentence

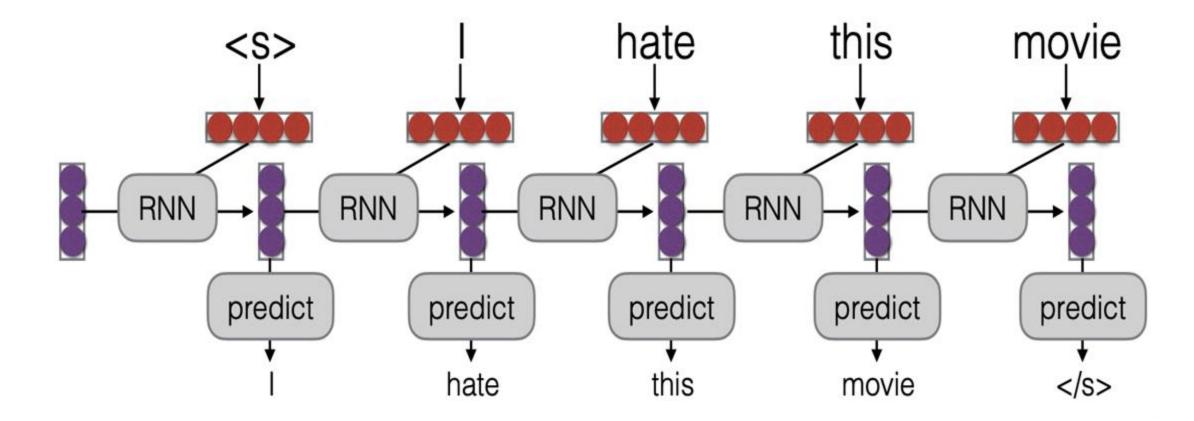
- Tagging
- Language modeling





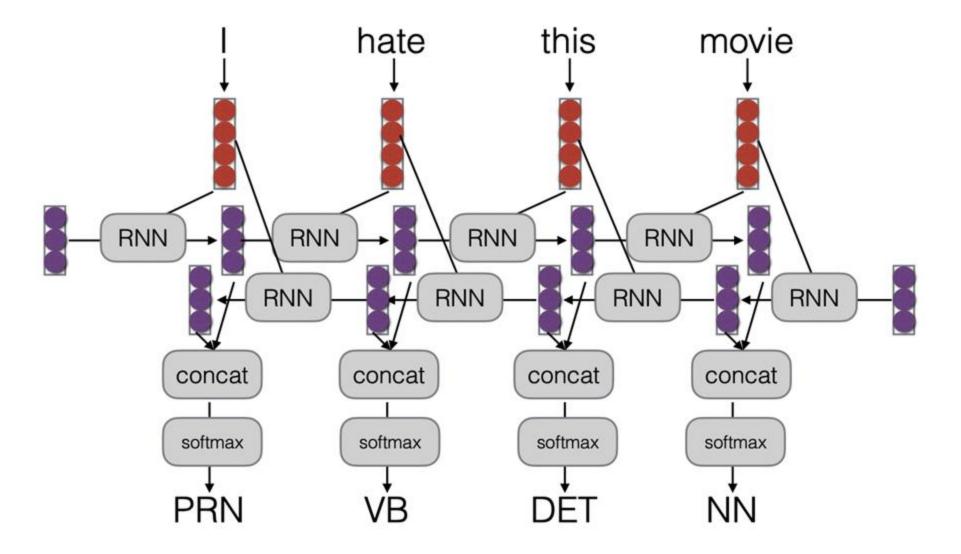
#### e.g., Language Modeling

Language modeling is like a tagging task, where each tag is the next word!





# e.g., POS Tagging with Bi-RNNs







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#### Vanishing Gradient

Gradients decrease as they get pushed back

 $\frac{dl}{d_{h_0}} = \operatorname{tiny} \quad \frac{dl}{d_{h_1}} = \operatorname{small} \quad \frac{dl}{d_{h_2}} = \operatorname{med.} \quad \frac{dl}{d_{h_3}} = \operatorname{large}$   $\begin{array}{c} \mathbf{h}_0 \rightarrow \mathbb{RNN} \rightarrow \mathbf{h}_1 \rightarrow \mathbb{RNN} \rightarrow \mathbf{h}_2 \rightarrow \mathbb{RNN} \rightarrow \mathbf{h}_3 \rightarrow \mathbb{square\_err} \rightarrow \mathcal{l} \\ \mathbf{x}_1 \qquad \mathbf{x}_2 \qquad \mathbf{x}_3 \qquad \mathbf{y}^{\star} \end{array}$ 

□ Why? "Squashed" by non-linearities or small weights in matrices





## A Solution: Long Short-term Memory (LSTM)

(Hochreiter and Schmidhuber 1997)

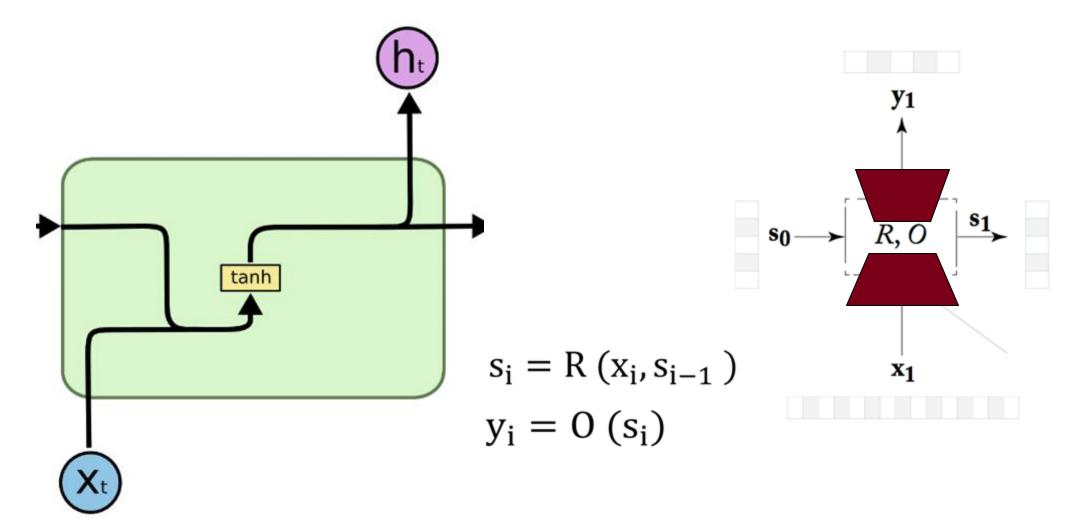
#### Make additive connections between time steps

Addition does not modify the gradient, no vanishing

#### **Gates** to control the information flow

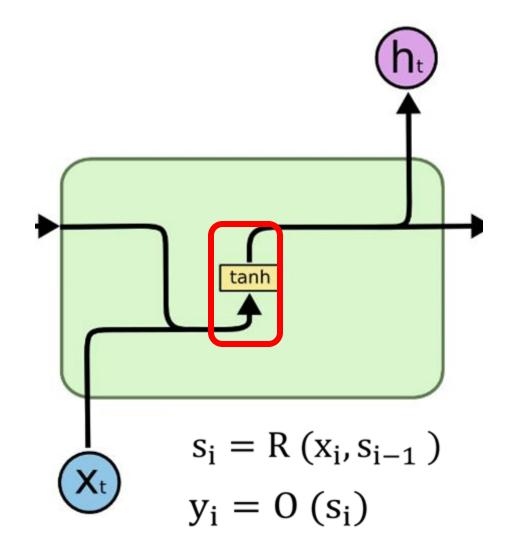


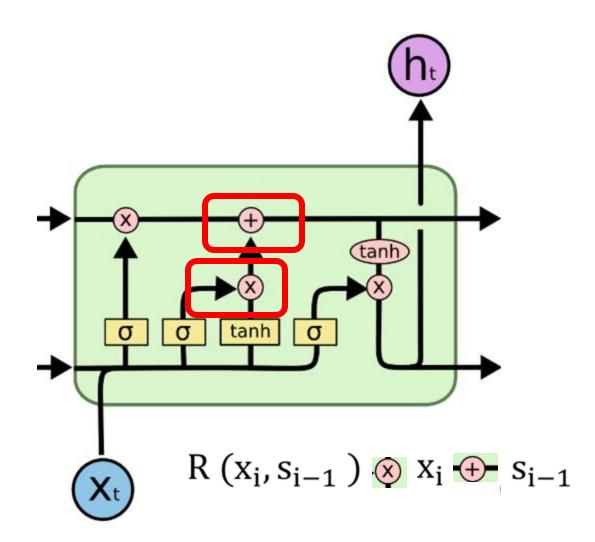
#### **RNN Structure**





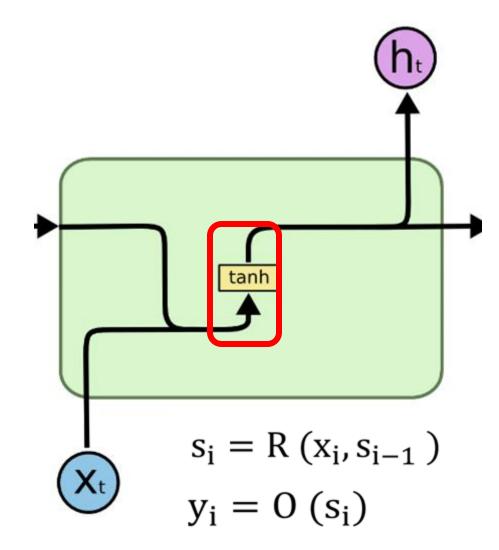
#### RNN vs LSTM Structure

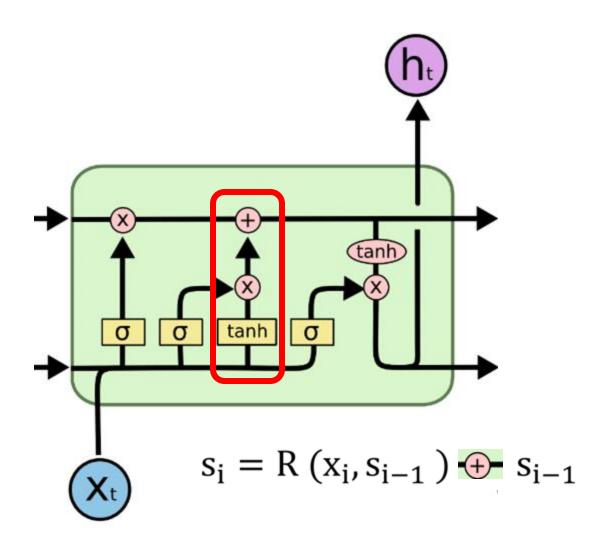






#### RNN vs LSTM Structure



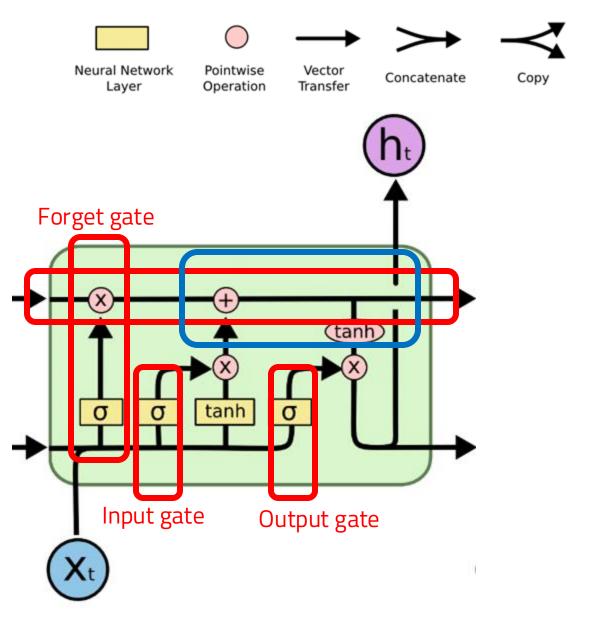




## LSTM Structure

- □ Forget gate: what value do we try to add/forget to the memory cell?
- □ Input gate: how much of the update do we allow to go through? Cell state
- Output gate: how much of the cell do we reflect in the next state?

$$egin{aligned} f_t &= \sigma_g(W_f x_t + U_f h_{t-1} + b_f) \ i_t &= \sigma_g(W_i x_t + U_i h_{t-1} + b_i) \ o_t &= \sigma_g(W_o x_t + U_o h_{t-1} + b_o) \ c_t &= f_t \circ c_{t-1} + i_t \circ \sigma_c(W_c x_t + U_c h_{t-1} + h_t) \ h_t &= o_t \circ \sigma_h(c_t) \end{aligned}$$



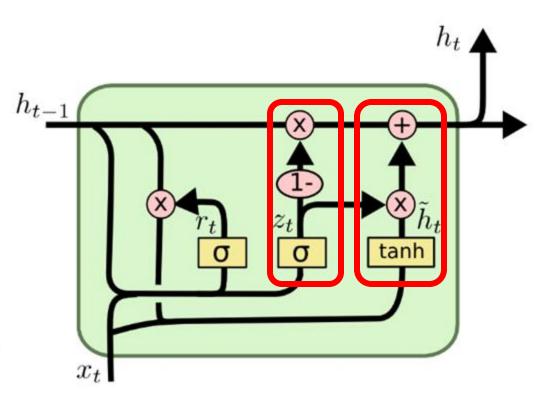


## LSTM variant: Gated Recurrent Unit (GRU)

(Cho et al., 2014)

- Combines the forget and input gates into a single "update gate."
- Merges the cell state and hidden state
- And, other small changes

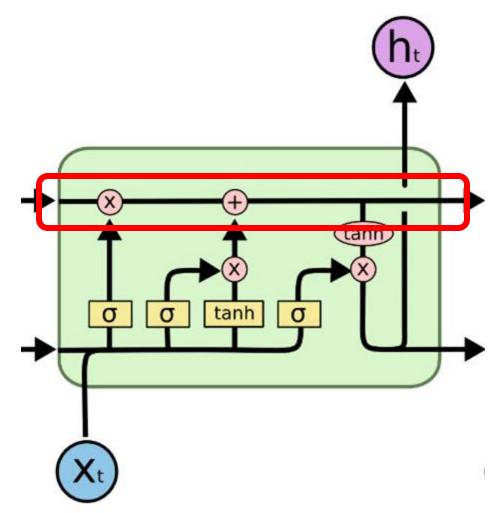
$$\begin{aligned} z_t &= \sigma_g(W_z x_t + U_z h_{t-1} + b_z) \\ r_t &= \sigma_g(W_r x_t + U_r h_{t-1} + b_r) \\ h_t &= \underbrace{(1 - z_t)}_{h_{t-1}} \circ h_{t-1} + \underbrace{z_t}_{h} \circ \sigma_h(W_h x_t + U_h(r_t \circ h_{t-1}) + b_h) \\ & \text{Additive or Non-linear} \end{aligned}$$





## Most Important Takeaway

- The Cell State is an information highway
- Gradient can flow over this without nearly as many issues of vanishing/exploding gradients that we saw in RNNs
- We are doing a better job at reducing the 'distance' between our loss function and each individual parameter





## A Solution: Long Short-term Memory (LSTM)

(Hochreiter and Schmidhuber 1997)

#### Make additive connections between time steps

Addition does not modify the gradient, no vanishing

#### **Gates** to control the information flow



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#### class RNN(nn.Module):

...

def \_\_init\_\_(self, input\_size: int, hidden\_size: int, output\_size: int) -> None: super().\_\_init\_\_()

```
self.i2h = nn.Linear(input_size, hidden_size, bias=False)
self.h2h = nn.Linear(hidden_size, hidden_size)
self.h2o = nn.Linear(hidden_size, output_size)
```

```
def forward(self, x, hidden_state) :

x = self.i2h(x)

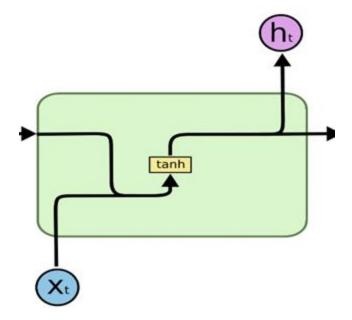
hidden_state = self.h2h(hidden_state)

hidden_state = torch.tanh(x + hidden_state)

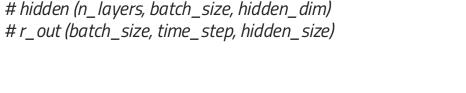
out = self.h2o(hidden_state)

y_i = O(s_i)

return out, hidden_state
```







# x (batch\_size, seq\_length, input\_size)



self.rnn = nn.RNN(input\_size, hidden\_dim, n\_layers, batch\_first=True)
self.fc = nn.Linear(hidden\_dim, output\_size)

def forward(self, x, hidden):
r\_out, hidden = self.rnn(x, hidden)
r\_out = r\_out.view(-1, self.hidden\_dim)
return self.fc(r\_out), hidden
y\_i = O(s\_i)

def \_\_init\_\_(self, input\_size, output\_size, hidden\_dim, n\_layers):
 super(RNN, self).\_\_init\_\_()

class RNN(nn.Module):

...



#### class LSTM (nn.Module):

**def** \_\_init\_\_(self, num\_classes, input\_size, hidden\_size, num\_layers, seq\_length):

```
super(LSTM1, self).__init__()
```

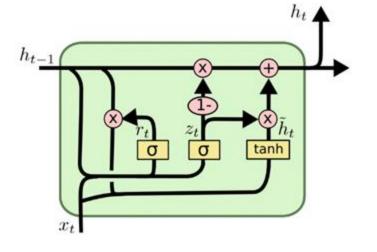
```
self.lstm = nn.LSTM(input_size=input_size, hidden_size=hidden_size,
num_layers=num_layers, batch_first=True)
self.fc = nn.Linear(hidden_size, num_classes)
self.relu = nn.ReLU()
```

#### def forward(self,x):

. . .

 $\begin{array}{l} h_0 = \text{Variable(torch.zeros(self.num_layers, x.size(0), self.hidden_size))} \\ c_0 = \text{Variable(torch.zeros(self.num_layers, x.size(0), self.hidden_size))} \\ \text{output, (hn, cn)} = \textbf{self.lstm}(x, (h_0, c_0)) \\ \text{hn} = \text{hn.view(-1, self.hidden_size)} \\ f_t = \sigma_g(W_t, v_t) \\ \text{return self.fc (self.relu(hn))} \\ \end{array}$ 

 $egin{aligned} f_t &= \sigma_g(W_f x_t + U_f h_{t-1} + b_f) \ i_t &= \sigma_g(W_i x_t + U_i h_{t-1} + b_i) \ o_t &= \sigma_g(W_o x_t + U_o h_{t-1} + b_o) \ c_t &= f_t \circ c_{t-1} + i_t \circ \sigma_c(W_c x_t + U_c h_{t-1} + b_c) \ h_t &= o_t \circ \sigma_h(c_t) \end{aligned}$ 



O PyTorch



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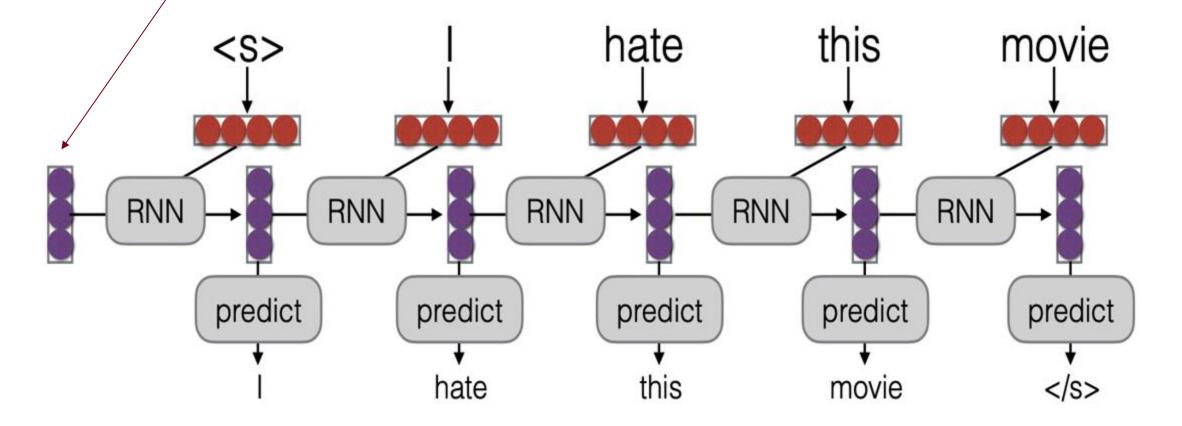
## Connecting RNN to RNN for sequence-to-sequence (seq2seq) modeling





#### RNN (decoder) for language modeling

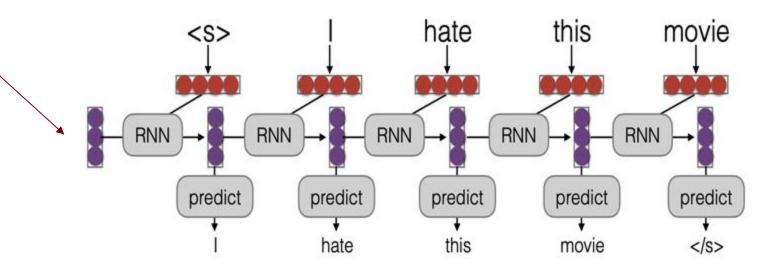
Randomly initialized hidden state  $h_t$  at time step t = 0





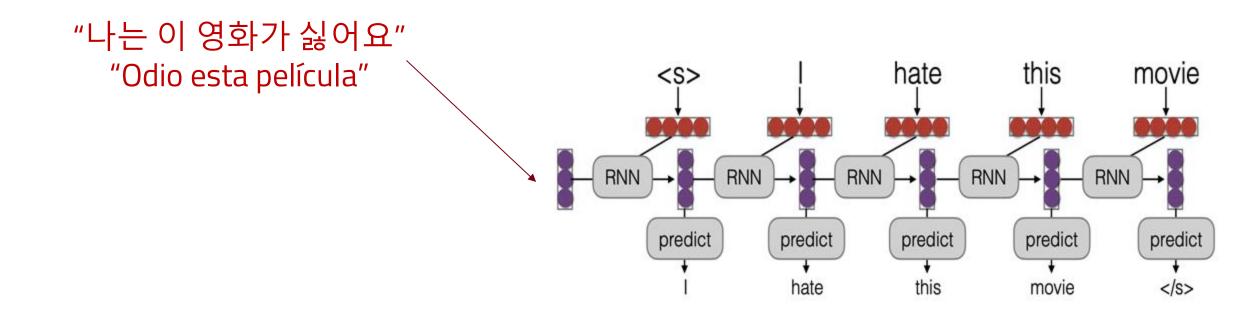
## RNN (decoder) for language modeling

What if we encode some specific context, instead of random state?



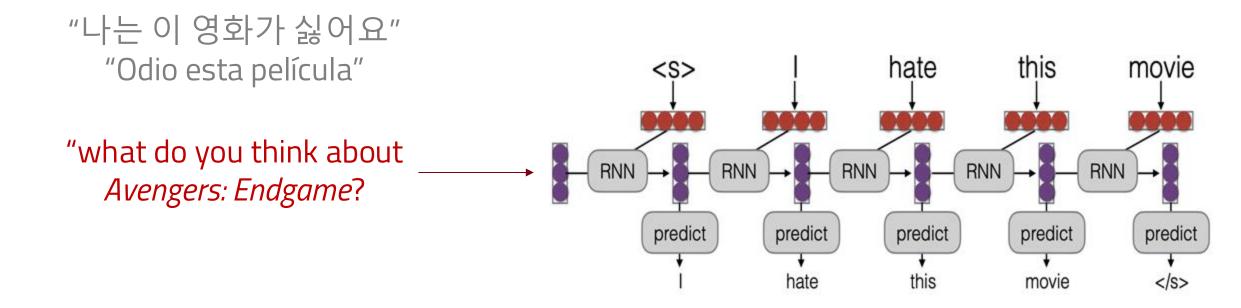


### RNN (encoder) - RNN (decoder) for machine translation





## RNN (encoder) - RNN (decoder) for dialogue generation





## RNN (encoder) - RNN (decoder) for question answering

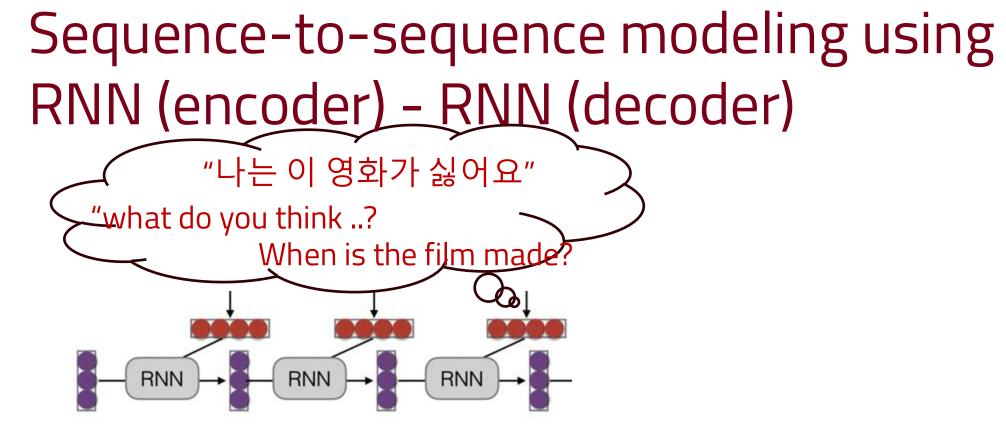
"나는 이 영화가 싫어요" "Odio esta película"

"what do you think about *Avengers: Endgame*? <S> This film is made in 1997
Image: Constrained and the second dependence of the seco

This film is made in 1997

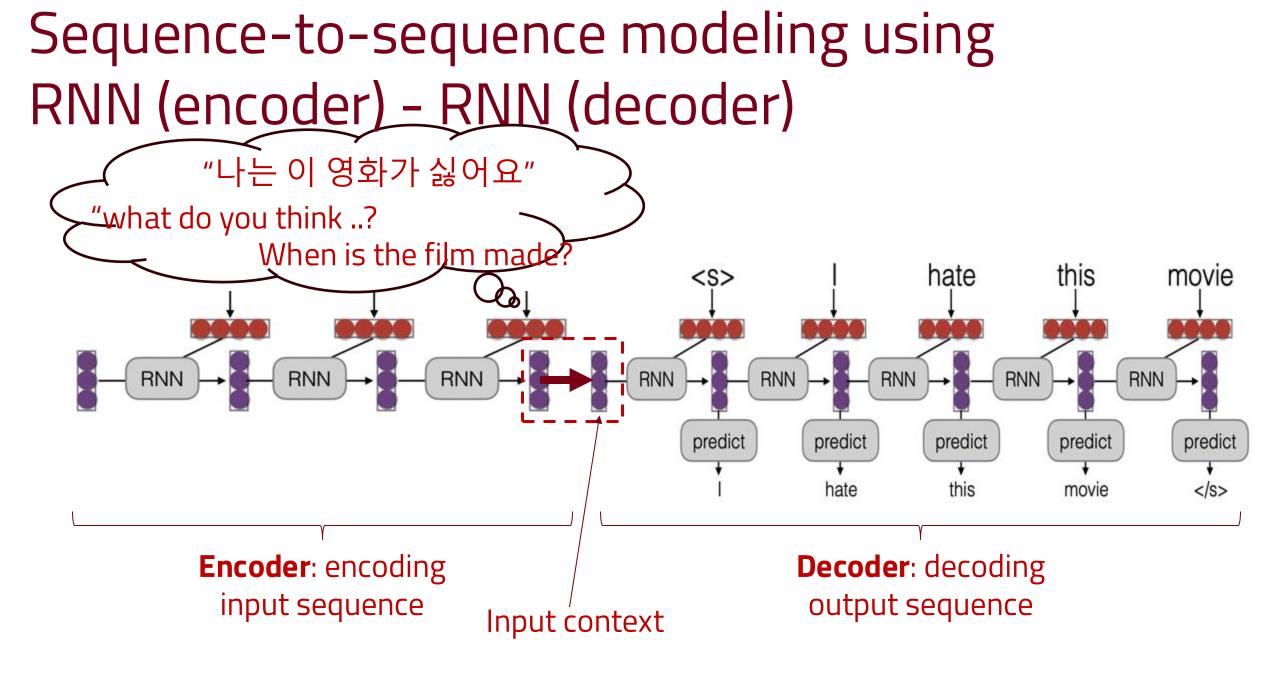
When is the film made?





## **Encoder**: encoding input sequence

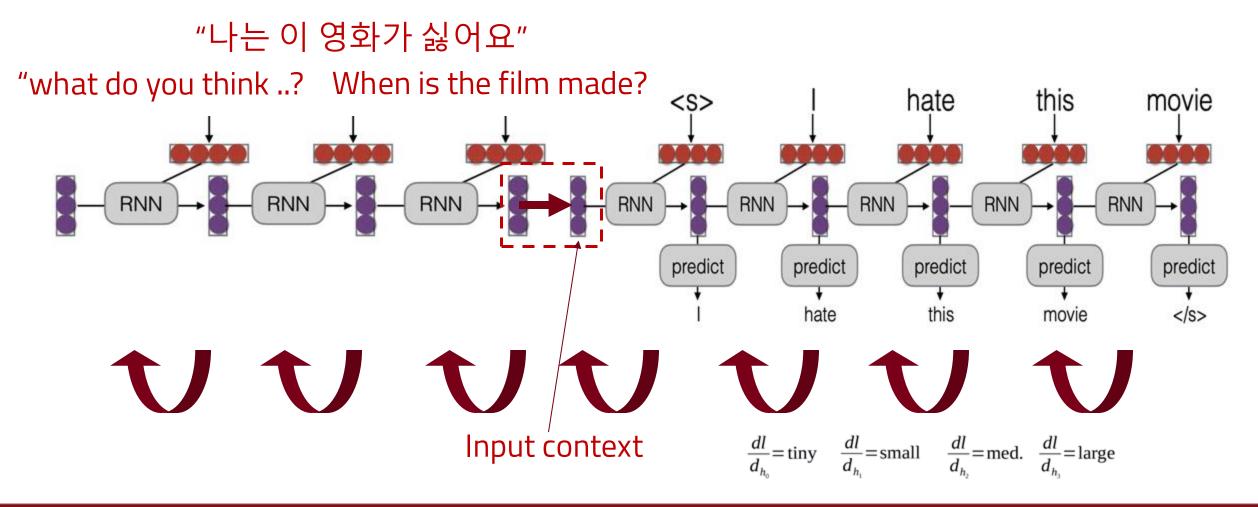




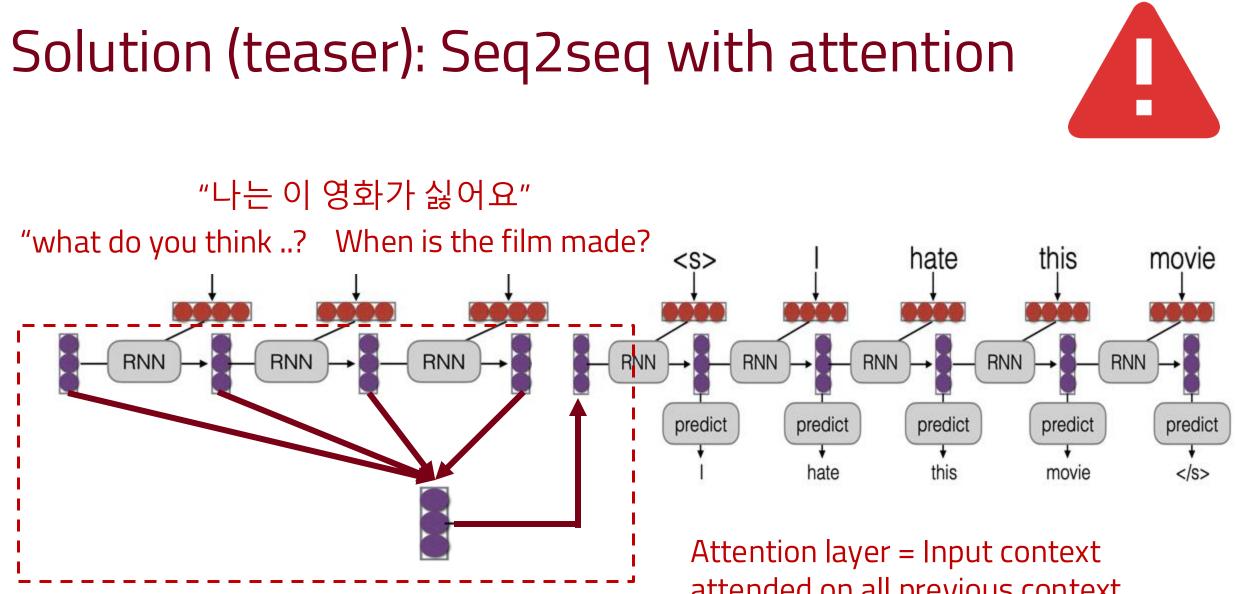


# Problem: forgetting input context as input gets longer









attended on all previous context (will be covered more in Transformer)



#### State-of-the-art Language Models





#### Teaser: Transformer-based LMs

#### □ SOTA LMs: GPT-2, Radford et al. 2018; GPT-3, Brown et al. 2020

Trigram	LSTM	GPT-2	GPT-3	
109	58.3	35.8	20.5	

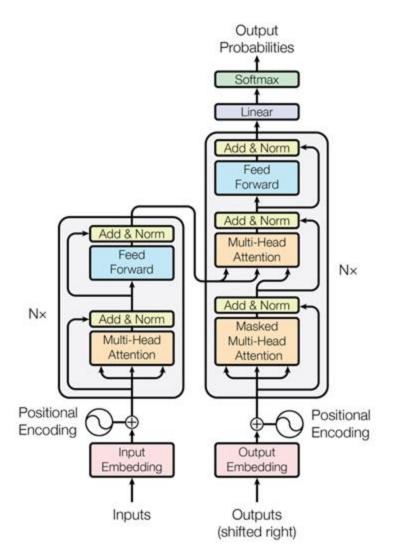
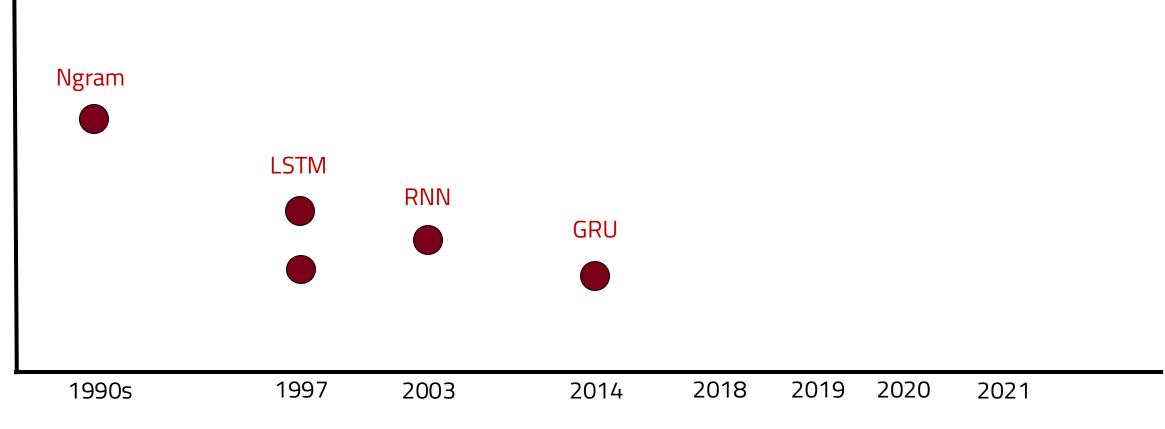


Figure 1: The Transformer - model architecture.

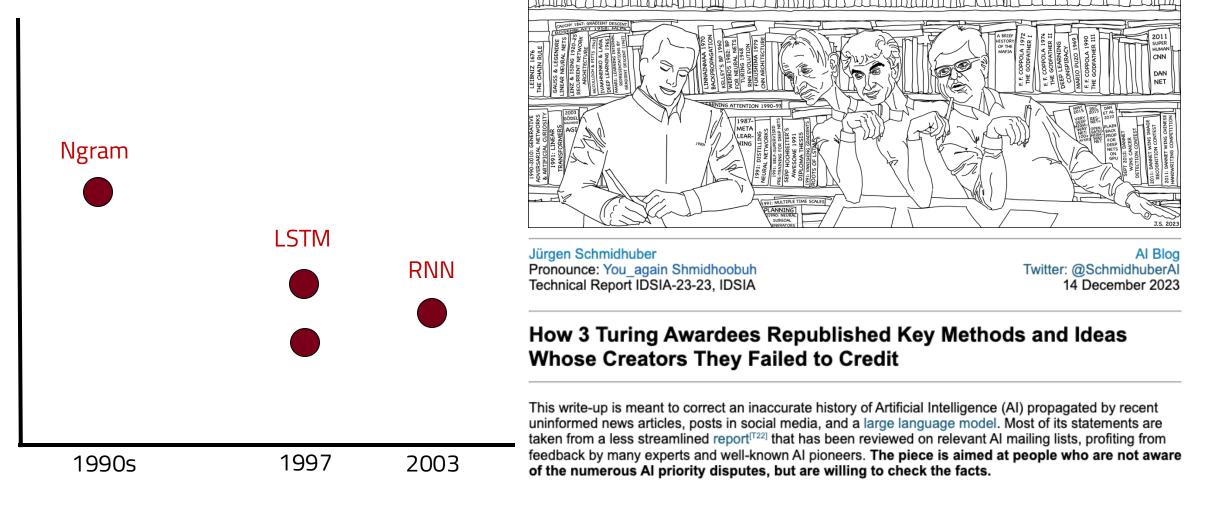




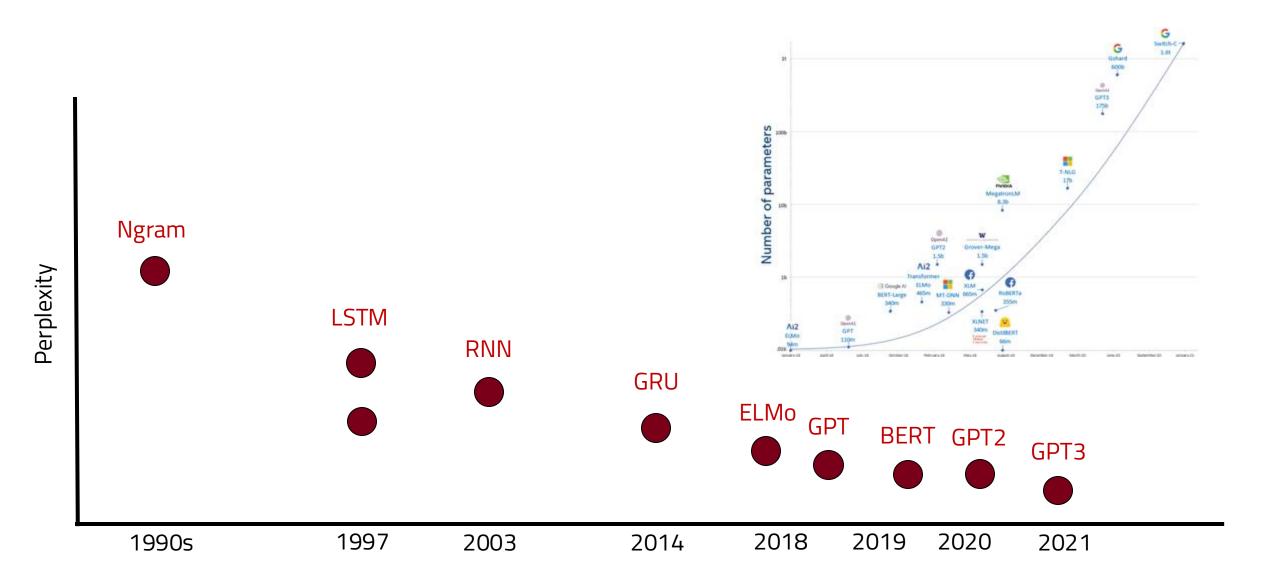








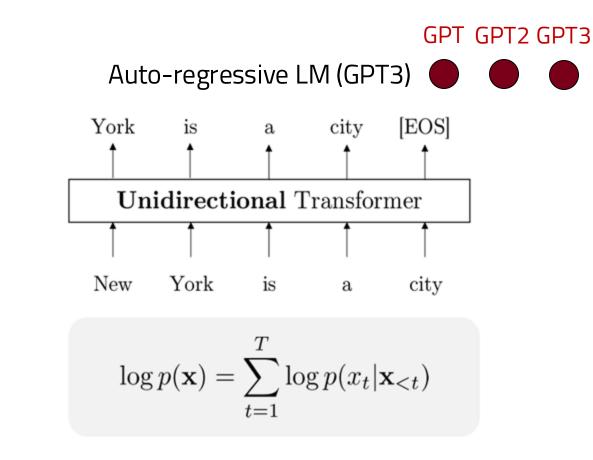




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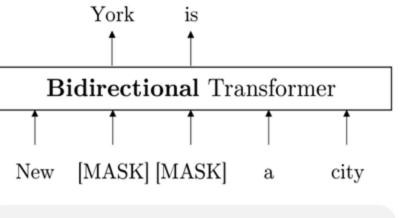


#### Teaser: Two Objectives for Language Model Pretraining



#### Next-token prediction

ELMo BERT Denoising autoencoding (BERT)



$$\log p(\bar{\mathbf{x}}|\hat{\mathbf{x}}) = \sum_{t=1}^{T} \operatorname{mask}_{t} \log p(x_{t}|\hat{\mathbf{x}})$$

#### Reconstruct masked tokens

Slides from Zihang Dai





Why better language models are useful?



## Language models can directly encode knowledge present in the training corpus.

The director of 2001: A Space Odyssey is \_\_\_\_\_





# Language models can directly encode knowledge present in the training corpus.

Query	Answer	Generation
Francesco Bartolomeo Conti was born in	Florence	Rome [-1.8], Florence [-1.8], Naples

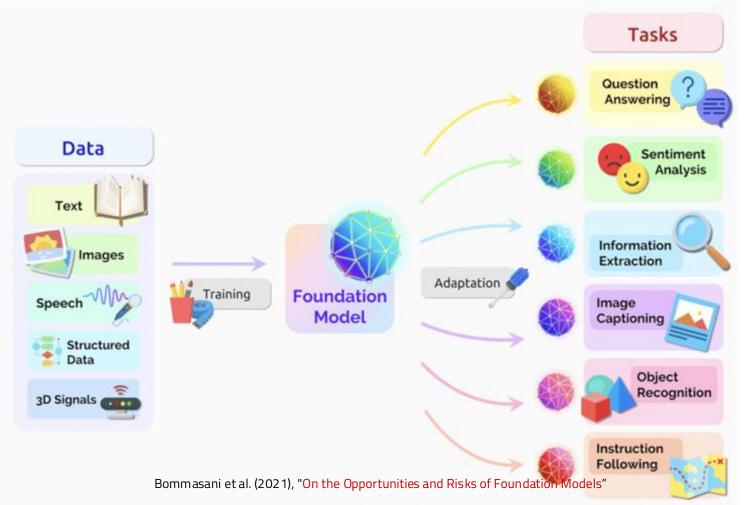


# Language models can directly encode knowledge present in the training corpus.

Query	Answer	Generation
Francesco Bartolomeo Conti was born in	Florence	Rome [-1.8], Florence [-1.8], Naples
Adolphe Adam died in	Paris	Paris [-0.5], London [-3.5], Vienna
English bulldog is a subclass of	dog	dogs [-0.3], breeds [-2.2], dog
The official language of Mauritius is	English	English [-0.6], French [-0.9], Arabic
Patrick Oboya plays in position.	midfielder	centre [-2.0], center [-2.2], midfielder
Hamburg Airport is named after	Hamburg	Hess [-7.0], Hermann [-7.1], Schmidt



## Language models can be a foundation for various tasks across different modalities







#### Language models are stochastic parrots



Bender et al. (2021), "On the Dangers of Stochastic Parrots: Can Language Models Be Too Big?"



